

Estimation of conditional mean squared error of prediction for claims triangle reserving

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The presented material is based on the preprint [6] co-authored with

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Aim with the talk:

- ▶ Provide a unified approach to conditional MSEP calculations
- ▶ Provide a computable “distribution-free” MSEP formula assuming only knowledge of lower order moments
- ▶ Give a number of examples on how to apply the method

Outline of the talk:

- ▶ Introduce Mack's definition of conditional MSEP and the general problem with frequentist "estimation error"
- ▶ Introduce a randomisation device for assessing the estimation error – conditional vs unconditional specification
- ▶ Derive a simple (semi-) analytical approximation formula for calculating conditional MSEP which only relies on lower order moments
- ▶ Examples: Mack's C-L, ultimo and CDR(k) calculations, ODP C-L etc.

If time allows:

- ▶ Relate different notions of parameter uncertainty – frequentist "estimation error" vs Bayesian "parameter uncertainty"
- ▶ Discuss model selection for auto-regressive reserving models – FPE and Mallows' C_p

Conditional MSEP

- ▶ Assume that we have a stochastic process S_t parametrised in terms of a parameter vector θ
- ▶ Let $\mathcal{F}_0 = \sigma\{S_t; t \leq 0\}$ denote the σ -algebra containing the information known up until today generated by the model S_t
- ▶ Let X denote a random quantity of interest which is a function of the evolution of S_t for $t > 0$
- ▶ A natural predictor of X is given by

$$\hat{X} := h(\hat{\theta}; \mathcal{F}_0),$$

where $h(\theta; \mathcal{F}_0) := \mathbb{E}[X \mid \mathcal{F}_0]$, and where $\hat{\theta}$ corresponds to some \mathcal{F}_0 -measurable estimator

- ▶ \hat{X} is often referred to as a “plug-in” estimator of X
- ▶ We will refer to the function $\mathbf{z} \mapsto h(\mathbf{z}; \mathcal{F}_0)$ as the “basis of prediction”

Conditional MSEP

Definition 1 (Conditional MSEP)

$$\text{MSEP}_{\mathcal{F}_0}(X, \hat{X}) := \mathbb{E}[(X - \hat{X})^2 \mid \mathcal{F}_0]$$

Note that Definition 1 is an L^2 -distance between a stochastic variable and its plug-in predictor.

We will only consider MSEP-calculations w.r.t. Definition 1

Conditional MSEP

Note that Definition 1 may be rewritten according to

$$\begin{aligned}\text{MSEP}_{\mathcal{F}_0}(X, \hat{X}) &:= \text{Var}(X \mid \mathcal{F}_0) + \mathbb{E}[(\mathbb{E}[\hat{X} \mid \mathcal{F}_0] - \mathbb{E}[X \mid \mathcal{F}_0])^2 \mid \mathcal{F}_0] \\ &= \text{Var}(X \mid \mathcal{F}_0) + \mathbb{E}[(h(\hat{\theta}; \mathcal{F}_0) - h(\theta; \mathcal{F}_0))^2 \mid \mathcal{F}_0] \\ &= \text{Var}(X \mid \mathcal{F}_0) + (h(\hat{\theta}; \mathcal{F}_0) - h(\theta; \mathcal{F}_0))^2.\end{aligned}$$

Moreover, note that

- ▶ “process variance”: $\text{Var}(X \mid \mathcal{F}_0) \geq 0$
- ▶ “estimation error”: $\mathbb{E}[(\mathbb{E}[\hat{X} \mid \mathcal{F}_0] - \mathbb{E}[X \mid \mathcal{F}_0])^2 \mid \mathcal{F}_0] \geq 0$
- ▶ if we let $H(\theta; \mathcal{F}_0) := \text{MSEP}_{\mathcal{F}_0}(X, \hat{X})(\theta)$, it follows that

$$\widehat{\text{MSEP}}_{\mathcal{F}_0}(X, \hat{X}) := H(\hat{\theta}; \mathcal{F}_0) = \widehat{\text{Var}}(X \mid \mathcal{F}_0),$$

i.e. the estimation error is 0 – clearly an underestimation

Conditional MSEP

Although the plug-in process variance may be hard to calculate in practice, it is usually well defined

We will henceforth focus on the plug-in estimation error

Calculating conditional MSEP

- ▶ **Suggested solution:** introduce a randomisation device
- ▶ That is, replace the \mathcal{F}_0 -measurable $\hat{\theta}$ with a randomised version $\hat{\theta}^*$ which is **not** \mathcal{F}_0 -measurable
- ▶ $\hat{\theta}^*$ should be chosen to share key properties with the original estimator $\hat{\theta}$
- ▶ In this way we only estimate how the parameter uncertainty from $\hat{\theta}^*$ propagates through $\mathbf{z} \mapsto h(\mathbf{z}; \mathcal{F}_0)$ – **keeping the basis of prediction fix**

Calculating conditional MSEP

- ▶ The specification of $\hat{\theta}^*$ should be based on the behaviour of $\hat{\theta}$
- ▶ Recall that our observed data is generated by the process S_t
- ▶ Let S_t^\perp correspond to an independent copy of S_t
 - ▶ S_t^\perp can be thought of as a “parallel universe”
- ▶ It is then natural to assume that $\hat{\theta}^*$ is defined in terms of S_t^\perp and possibly S_t

Calculating conditional MSEP

Regarding the construction of $\widehat{\boldsymbol{\theta}}^*$ we will make the following assumption:

Assumption 1

Assume that

$$X \perp \widehat{\boldsymbol{\theta}}^* \mid \mathcal{F}_0$$

Definition 2

$$\begin{aligned} \text{MSEP}_{\mathcal{F}_0}^*(X, \widehat{X}) &:= \mathbb{E}[(X - \widehat{X}^*)^2 \mid \mathcal{F}_0] \\ &= \text{Var}(X \mid \mathcal{F}_0) + \mathbb{E}[(h(\widehat{\boldsymbol{\theta}}^*; \mathcal{F}_0) - h(\boldsymbol{\theta}; \mathcal{F}_0))^2 \mid \mathcal{F}_0] \end{aligned}$$

Note that Assumption 1 is fulfilled if we let $\widehat{\boldsymbol{\theta}}^* = \widehat{\boldsymbol{\theta}}^\perp$, i.e. only resample based on S_t^\perp

Calculating conditional MSEF

Before we proceed any further, we will recall the definition of the “final prediction error” (FPE) introduced by Akaike in [1, 2]:

- ▶ Let \mathcal{F}_0^\perp denote the filtration generated by S_t^\perp , and let X^\perp denote the S_t^\perp analog of X
- ▶ The **unconditional** FPE of \hat{X} is then given by

$$\text{FPE}(X, \hat{X}) := \mathbb{E}[(X^\perp - h(\hat{\theta}; \mathcal{F}_0^\perp))^2],$$

where $\hat{\theta}$ is calculated based on S_t being \mathcal{F}_0 -measurable, but not \mathcal{F}_0^\perp -measurable

- ▶ Note that due to the exchangeability between S_t and S_t^\perp it follows that

$$\text{FPE}(X, \hat{X}) := \mathbb{E}[(X - h(\hat{\theta}^\perp; \mathcal{F}_0))^2]$$

Calculating conditional MSEF

- ▶ The **conditional** FPE of \widehat{X} is then given by

$$\begin{aligned}\text{FPE}_{\mathcal{F}_0^\perp}(X, \widehat{X}) &:= \mathbb{E}[(X^\perp - h(\widehat{\theta}; \mathcal{F}_0^\perp))^2 \mid \mathcal{F}_0^\perp] \\ &= \mathbb{E}[(X - h(\widehat{\theta}^\perp; \mathcal{F}_0))^2 \mid \mathcal{F}_0]\end{aligned}$$

- ▶ That is, given that $\widehat{\theta}^* = \widehat{\theta}^\perp$ it holds that

$$\text{MSEF}_{\mathcal{F}_0}^*(X, \widehat{X}) = \text{FPE}_{\mathcal{F}_0}(X, \widehat{X}),$$

which is a well studied object for model selection for auto-regressive time series models!

Calculating conditional MSEP

- ▶ If we are interested in e.g. “distribution-free” reserving models the unconditional behaviour of $\hat{\theta}$, and hence $\hat{\theta}^\perp$, is not always computationally tractable
- ▶ Akaike circumvented this issue for auto-regressive time series models, by taking the limit of the sample size
- ▶ For conditional models an alternative is to use a conditional specification of $\hat{\theta}^*$ which differs from $\hat{\theta}^\perp$
- ▶ Moreover, we are often interested in situations where we only make assumptions on moments, not specifying the full distribution of $\hat{\theta}$ (and hence $\hat{\theta}^*$) completely

Calculating conditional MSEP

If we make a **single** first-order Taylor expansion of $h(\boldsymbol{\theta}; \mathcal{F}_0)$ we get

$$\begin{aligned} \text{MSEP}_{\mathcal{F}_0}^{*, \nabla}(X, \widehat{X}) &:= \text{Var}(X \mid \mathcal{F}_0) \\ &\quad + \nabla h(\boldsymbol{\theta}; \mathcal{F}_0)' \mathbb{E}[(\widehat{\boldsymbol{\theta}}^* - \boldsymbol{\theta})^2 \mid \mathcal{F}_0] \nabla h(\boldsymbol{\theta}; \mathcal{F}_0) \end{aligned}$$

Note that $\text{MSEP}_{\mathcal{F}_0}^{*, \nabla}(X, \widehat{X})$ is

- ▶ expressed in terms of conditional moments \Rightarrow “distribution-free”
- ▶ based on a **single** first-order Taylor expansion

Calculating conditional MSEP

We will henceforth

- ▶ focus on the calculation of $\text{MSEP}_{\mathcal{F}_0}^{*,\nabla}(X, \hat{X})$
- ▶ assume that $\nabla h(\boldsymbol{\theta}; \mathcal{F}_0)$ exists
- ▶ **make no further approximations!!**

We will continue with the specification of $\hat{\boldsymbol{\theta}}^*$ in terms of assumptions on moments of $\hat{\boldsymbol{\theta}}$

Specification of $\hat{\theta}^*$: moment assumptions

Assumption 2 (Unconditional structure)

Assume that

$$\begin{aligned}\mathbb{E}[\hat{\theta}] &= \theta, \\ \text{Cov}(\hat{\theta}) &< \infty \quad \text{a.s.}\end{aligned}$$

Note that given Assumption 2 it follows that

$$\begin{aligned}\mathbb{E}[\hat{\theta}^\perp] &= \mathbb{E}[\hat{\theta}] = \theta, \\ \text{Cov}(\hat{\theta}^\perp) &= \text{Cov}(\hat{\theta}) < \infty \quad \text{a.s.}\end{aligned}$$

Specification of $\hat{\theta}^*$: moment assumptions

Assumption 3 (Conditional structure)

Let $\theta = (\theta_1, \dots, \theta_p)$ and let $\mathcal{G}_k \subset \mathcal{F}_0$, $k = 1, \dots, p$ and assume that $\mathcal{G}_j \subset \mathcal{G}_k$, $j < k$ together with

$$\mathbb{E}[\hat{\theta}_k | \mathcal{G}_k] = \theta_k,$$

$$C_{j,k}(\hat{\theta}) := \text{Cov}(\hat{\theta}_j, \hat{\theta}_k | \mathcal{G}_j, \mathcal{G}_k) < \infty,$$

holds for all $j, k = 1, \dots, p$ and that

$$\chi(\theta; \mathcal{F}_0) := \begin{bmatrix} C_{1,1}(\hat{\theta}) & C_{1,2}(\hat{\theta}) & \dots & C_{1,p}(\hat{\theta}) \\ C_{1,2}(\hat{\theta}) & \ddots & & \\ \vdots & & & \\ C_{1,p}(\hat{\theta}) & & & C_{p,p}(\hat{\theta}) \end{bmatrix},$$

corresponds to a proper covariance matrix.

Specification of $\widehat{\boldsymbol{\theta}}^*$: moment assumptions

Note that the distribution-free CL model fulfil Assumption 3

Given Assumption 3, let $\widehat{\boldsymbol{\theta}}^{*,c}$ be defined as a randomised version of $\widehat{\boldsymbol{\theta}}$ so that

$$\begin{aligned}\mathbb{E}[\widehat{\boldsymbol{\theta}}_k^{*,c} \mid \mathcal{F}_0] &= \mathbb{E}[\widehat{\boldsymbol{\theta}}_k \mid \mathcal{G}_k] = \boldsymbol{\theta}_k, \\ \text{Cov}(\widehat{\boldsymbol{\theta}}_j^{*,c}, \widehat{\boldsymbol{\theta}}_k^{*,c} \mid \mathcal{F}_0) &= \text{Cov}(\widehat{\boldsymbol{\theta}}_j, \widehat{\boldsymbol{\theta}}_k \mid \mathcal{G}_j, \mathcal{G}_k) < \infty,\end{aligned}$$

holds for all $j, k = 1, \dots, p$. That is,

$$\text{Cov}(\widehat{\boldsymbol{\theta}}^{*,c} \mid \mathcal{F}_0) = \chi(\boldsymbol{\theta}; \mathcal{F}_0).$$

Specification of $\hat{\theta}^*$: moment assumptions

Note that

- ▶ $\hat{\theta}^{*,c}$ fulfilling Assumption 3 may be constructed using a mixture of S_t and S_t^\perp — an example of such a construction for the distribution-free CL model is given in [3]
- ▶ the conditional construction of $\hat{\theta}^*$ is in general not meaningful without a specific naturally conditional/partitioned model structure or an ancillarity-like argument
- ▶ we have the following unbiasedness relations between $\hat{\theta}^{*,c}$ and $\hat{\theta}^\perp$:

$$\begin{aligned}\mathbb{E}[\mathbb{E}[\hat{\theta}_k^{*,c} \mid \mathcal{F}_0]] &= \mathbb{E}[\hat{\theta}_k^\perp] \\ \mathbb{E}[\text{Cov}(\hat{\theta}_j^{*,c}, \hat{\theta}_k^{*,c} \mid \mathcal{F}_0)] &= \text{Cov}(\hat{\theta}_j^\perp, \hat{\theta}_k^\perp)\end{aligned}$$

Specification of $\widehat{\boldsymbol{\theta}}^*$: moment assumptions

Further, regardless of the specification of $\widehat{\boldsymbol{\theta}}^*$ it holds that

$$\begin{aligned}\text{MSEP}_{\mathcal{F}_0}^{*,\nabla}(X, \widehat{X}) &:= H^{*,\nabla}(\boldsymbol{\theta}; \mathcal{F}_0) \\ &= \text{Var}(X \mid \mathcal{F}_0) \\ &\quad + \nabla h(\boldsymbol{\theta}; \mathcal{F}_0)' \Lambda(\boldsymbol{\theta}; \mathcal{F}_0) \nabla h(\boldsymbol{\theta}; \mathcal{F}_0)\end{aligned}$$

where

$$\Lambda(\boldsymbol{\theta}; \mathcal{F}_0) := \text{Cov}(\widehat{\boldsymbol{\theta}}^* \mid \mathcal{F}_0).$$

That is

$$\widehat{\text{MSEP}}_{\mathcal{F}_0}(X, \widehat{X}) := H^{*,\nabla}(\widehat{\boldsymbol{\theta}}; \mathcal{F}_0) \quad (1)$$

is a distribution-free computable MSEP-estimator using either of the two specifications of $\widehat{\boldsymbol{\theta}}^*$

Specification of $\hat{\theta}^*$: moment assumptions

- ▶ Note that the computable MSEP estimator given by (1) does not rely on that $\hat{\theta}^*$ is constructed explicitly!
- ▶ It is enough to have the above theoretical construction together with that the above moments in terms of $\hat{\theta}$ are computable!
 - ▶ This is the approach taken in [4] for the distribution-free CL model — “pseudo-estimators”
- ▶ For other more or less explicit constructions of (conditional) $\hat{\theta}^*$ for the distribution-free CL model, see e.g. [3, 8]
- ▶ See also [6] for explicit constructions of $\hat{\theta}^*$ for more general models

Applications

Applications: ultimo and CDR(k)

The outstanding claims reserve R_i for accident year i that is not yet fully developed when time is indexed in agreement with \mathcal{F}_0 :

$$R_i := \sum_{j=J-i+2}^J I_{i,j} = C_{i,J} - C_{i,J-i+1}, \quad R := \sum_{i=2}^J R_i.$$

The ultimate claim amount U_i for accident year i that is not yet fully developed:

$$U_i := \sum_{j=1}^J I_{i,j} = C_{i,J}, \quad U := \sum_{i=2}^J U_i.$$

The amount of paid claims P_i for accident year i that is not yet fully developed:

$$P_i := \sum_{j=1}^{J-i+1} I_{i,j} = C_{i,J-i+1}, \quad P := \sum_{i=2}^J P_i.$$

Obviously, $U_i = P_i + R_i$ and $U = P + R$.

Applications: ultimo and CDR(k)

Warm up – still no models:

Ultimo:

- ▶ $h(\boldsymbol{\theta}; \mathcal{F}_0) := \mathbb{E}[U \mid \mathcal{F}_0]$
- ▶ $\hat{U} := h(\hat{\boldsymbol{\theta}}; \mathcal{F}_0)$
- ▶ $\text{MSEP}_{\mathcal{F}_0}(U, \hat{U})(\boldsymbol{\theta}) = \text{MSEP}_{\mathcal{F}_0}(R, \hat{R})(\boldsymbol{\theta})$
- ▶ $\widehat{\text{MSEP}}_{\mathcal{F}_0}(U, \hat{U}) = \widehat{\text{MSEP}}_{\mathcal{F}_0}^{*, \nabla}(U, \hat{U})(\hat{\boldsymbol{\theta}})$

Applications: ultimo and CDR(k)

CDR(k):

▶ $h^{(0)}(\boldsymbol{\theta}; \mathcal{F}_0) := \mathbb{E}[U \mid \mathcal{F}_0]$, $h^{(k)}(\boldsymbol{\theta}; \mathcal{F}_k) := \mathbb{E}[U \mid \mathcal{F}_k]$

▶ $\text{CDR}(k) := h^{(0)}(\hat{\boldsymbol{\theta}}^{(0)}; \mathcal{F}_0) - h^{(k)}(\hat{\boldsymbol{\theta}}^{(k)}; \mathcal{F}_k)$

$$\implies h(\boldsymbol{\theta}; \mathcal{F}_0) := \mathbb{E}[\text{CDR}(k) \mid \mathcal{F}_0](\boldsymbol{\theta})$$

$$= h^{(0)}(\hat{\boldsymbol{\theta}}^{(0)}; \mathcal{F}_0) - \mathbb{E}[h^{(k)}(\hat{\boldsymbol{\theta}}^{(k)}; \mathcal{F}_k) \mid \mathcal{F}_0](\boldsymbol{\theta})$$

$$\implies \widehat{\text{CDR}}(k) := h(\hat{\boldsymbol{\theta}}^{(0)}; \mathcal{F}_0)$$

▶ $\widehat{\text{MSEP}}_{\mathcal{F}_0}(\text{CDR}(k), \widehat{\text{CDR}}(k)) =$
 $\text{MSEP}_{\mathcal{F}_0}^{*, \nabla}(\text{CDR}(k), \widehat{\text{CDR}}(k))(\hat{\boldsymbol{\theta}}^{(0)})$

Applications: ultimo and $\text{CDR}(k)$

Note that

- ▶ $h^{(0)}(\hat{\theta}^{(0)}; \mathcal{F}_0)$ is \mathcal{F}_0 -measurable \Leftrightarrow **part of the basis of prediction!!**
- ▶ MSEP for the ultimo claim amount is consistently defined with that of $\text{CDR}(k)$
- ▶ the definition of MSEP for the $\text{CDR}(k)$ differ from those used in e.g. [3, 4] for the distribution-free CL model — we only resample w.r.t. θ in $h(\theta; \mathcal{F}_0) := \mathbb{E}[\text{CDR}(k) \mid \mathcal{F}_0](\theta)$

Applications: the distribution-free CL model

Assume that, for $j = 1, \dots, J - 1$, there exist constants $f_j > 0$ and constants $\sigma_j^2 \geq 0$ such that

$$\begin{aligned}\mathbb{E}[C_{i,j+1} \mid C_{i,j}, \dots, C_{i,1}] &= f_j C_{i,j}, \\ \text{Var}(C_{i,j+1} \mid C_{i,j}, \dots, C_{i,1}) &= \sigma_j^2 C_{i,j},\end{aligned}$$

where $i = i_0, \dots, J$, and assume that,

$\{C_{i_0,1}, \dots, C_{i_0,J}\}, \dots, \{C_{J,1}, \dots, C_{J,J}\}$ are independent.

We will focus on MSEP for the ultimo claim amount

Applications: the distribution-free CL model

By using the above defining relations together with the tower property of conditional expectations yields

$$h_i(\mathbf{f}; \mathcal{F}_0) := \mathbb{E}[U_i | \mathcal{F}_0] = C_{i, J-i+1} \prod_{j=J-i+1}^{J-1} f_j,$$

$$h(\mathbf{f}; \mathcal{F}_0) := \mathbb{E}[U | \mathcal{F}_0] = \sum_{i=2}^J h_i(\mathbf{f}; \mathcal{F}_0).$$

Note that the distribution-free CL model is defined conditionally — define $\hat{\mathbf{f}}^*$ conditionally!!

Applications: the distribution-free CL model

That is,

$$\hat{f}_j = \frac{\sum_{i=i_0}^{J-j} C_{i,j+1}}{\sum_{i=i_0}^{J-j} C_{i,j}},$$

and let B_j denote the j first columns of the claims triangle defining \mathcal{F}_0

Let $\hat{\mathbf{f}}^*$ be defined so that

$$\mathbb{E}[\hat{f}_j^* | \mathcal{F}_0] = \mathbb{E}[\hat{f}_j | B_j] = f_j,$$

$$\text{Var}(\hat{f}_j^* | \mathcal{F}_0) = \{\mathbf{\Lambda}(\boldsymbol{\sigma}; \mathcal{F}_0)\}_{j,j} = \text{Var}(\hat{f}_j | B_j) = \frac{\sigma_j^2}{\sum_{i=i_0}^{J-j} C_{i,j}},$$

where $\{\mathbf{\Lambda}(\boldsymbol{\sigma}; \mathcal{F}_0)\}_{i,j} = 0$ for all $i \neq j$.

Applications: the distribution-free CL model

Want to calculate $\widehat{\text{MSEP}}_{\mathcal{F}_0}^{*,\nabla}(U, \widehat{U})$:

- ▶ Process variance? Given in [7]
- ▶ $\nabla h(\mathbf{f}; \mathcal{F}_0)$? Simple calculations!

$$\Rightarrow \{\nabla_{\mathbf{f}} h_i(\mathbf{f}; \mathcal{F}_0)\}_j = 1_{\{J-i+1 \leq j\}} C_{i,J-i+1} \frac{1}{f_j} \prod_{l=J-i+1}^{J-1} f_l,$$

for $i = 2, \dots, J$ and $j = 1, \dots, J-1$

Applications: the distribution-free CL model

By combining the above and simplifying gives us the following:

Proposition 1

$\widehat{\text{MSEP}}_{\mathcal{F}_0}^{*,\nabla}(U, \hat{U})$ from (1) is equal to the MSEP given in [7] for the distribution-free CL model.

How about if we would use an unconditional specification of $\hat{\mathbf{f}}^*$?

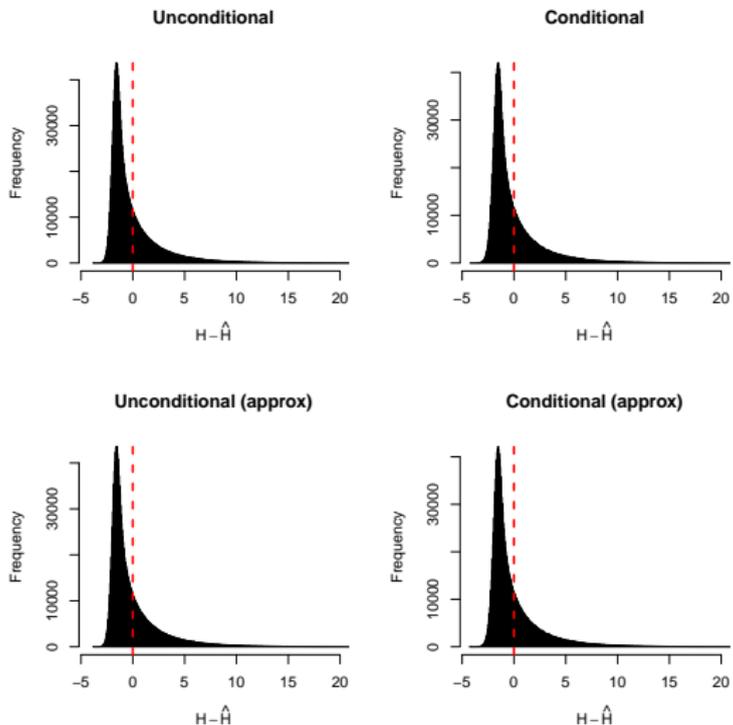


Figure: Illustration of conditional and unconditional specification of $\hat{\theta}^*$ for Mack's C-L based on Taylor-Ashe '83 data.

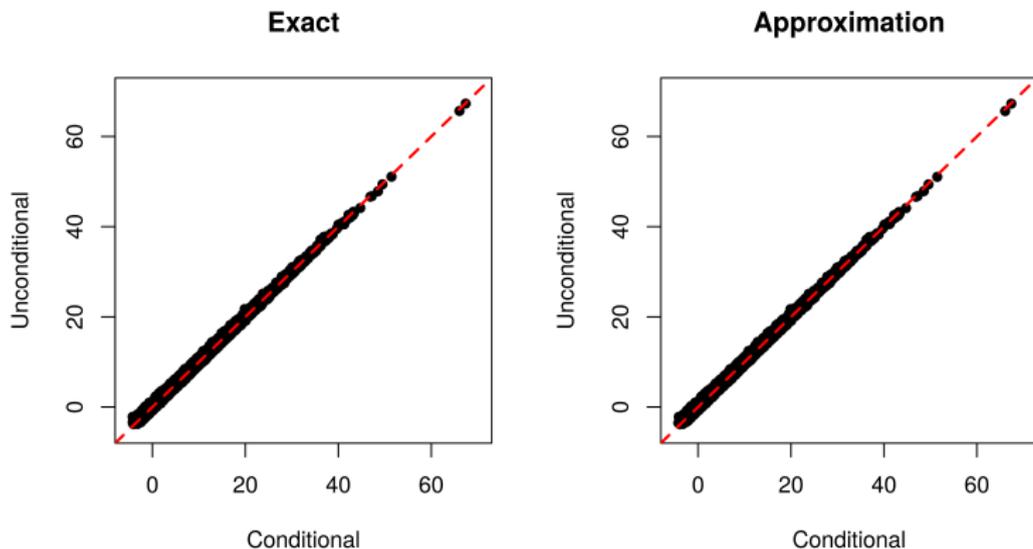


Figure: Illustration of conditional and unconditional specification of $\hat{\theta}^*$ for Mack's C-L based on Taylor-Ashe '83 data.

Applications: the distribution-free CL model

- ▶ It is possible to show that the conditional specification of $\hat{\theta}^*$ in line with Assumption 3 is an **unbiased estimator of the unconditional dito** (in fact holds for a wider class of models)
- ▶ It is possible to show that both specifications will be close given a sufficient amount of data (asym. consistent)
- ▶ $CDR(k)$ can be calculated in an analogous manner, but more involved calculations — skip!

Applications: over-dispersed CL model

Assume that

$$\begin{aligned}\mathbb{E}[I_{i,j}] &= \mu_{i,j}, \\ \text{Var}(I_{i,j}) &= \phi\mu_{i,j},\end{aligned}$$

where

$$\log(\mu_{i,j}) = \eta + \alpha_i + \beta_j, \quad \alpha_1 = \beta_1 = 0.$$

Note that the above is a model defined **unconditionally!**

MSEP for the ultimo claim amount?

Applications: over-dispersed CL model

$$h_i(\boldsymbol{\theta}; \mathcal{F}_0) = \mathbb{E}[U_i | \mathcal{F}_0] = C_{i,l-i} + \sum_{j=l-i+1}^J \mu_{i,j} = C_{i,l-i} + g_i(\boldsymbol{\theta}),$$

where $\boldsymbol{\theta} = (\eta, \{\alpha_i\}, \{\beta_k\})$, from which it follows that

$$\nabla h(\boldsymbol{\theta}; \mathcal{F}_0) = \nabla g(\boldsymbol{\theta})$$

and similarly it follows that $\text{Var}(U | \mathcal{F}_0) = \text{Var}(R)$, where R is indexed in time in agreement with \mathcal{F}_0

Applications: over-dispersed CL model

In a bit more detail, we have that:

$$\frac{\partial}{\partial \eta} h_i(\boldsymbol{\theta}; \mathcal{F}_0) = \frac{\partial}{\partial \eta} g_i(\boldsymbol{\theta}) = \sum_{j=l-i+1}^J \mu_{i,j},$$

$$\frac{\partial}{\partial \alpha_k} h_i(\boldsymbol{\theta}; \mathcal{F}_0) = \frac{\partial}{\partial \alpha_k} g_i(\boldsymbol{\theta}) = \sum_{j=l-i+1}^J \mathbf{1}_{\{i=k\}} \mu_{i,j},$$

$$\frac{\partial}{\partial \beta_k} h_i(\boldsymbol{\theta}; \mathcal{F}_0) = \frac{\partial}{\partial \beta_k} g_i(\boldsymbol{\theta}) = \sum_{j=l-i+1}^J \mathbf{1}_{\{j=k\}} \mu_{i,j},$$

$$\text{Var}(U_i | \mathcal{F}_0) = \text{Var}(R_i) = \phi \sum_{j=l-i+1}^J \mu_{i,j}.$$

Applications: over-dispersed CL model

Thus, by simplifying the MSEP-estimator from (1) we get

$$\begin{aligned}\widehat{\text{MSEP}}_{\mathcal{F}_0}(U, \hat{U}) &= \widehat{\text{MSEP}}(R, \hat{R}) \\ &= \sum_{i=2}^J \text{Var}(R_i)(\hat{\theta}) + \sum_{i=2}^J \nabla g_i(\hat{\theta})' \mathbf{\Lambda}(\hat{\theta}) \nabla g_i(\hat{\theta}) \\ &\quad + 2 \sum_{2 \leq i < k \leq j} \nabla g_i(\hat{\theta})' \mathbf{\Lambda}(\hat{\theta}) \nabla g_k(\hat{\theta}).\end{aligned}\quad (2)$$

Applications: over-dispersed CL model

Note that

- ▶ $\Lambda(\hat{\theta})$ is not available analytically, but is approximated when using standard GLM-fitting procedures \Rightarrow (2) is semi-analytical!
- ▶ the MSEP-estimator from (2) coincides with that from [5]
- ▶ the notion of MSEP reduces to the unconditional FPE — as wanted

Summary

- ▶ We have discussed how to calculate the conditional MSEP for (claims triangle based) reserving models
- ▶ We introduced a certain randomisation procedure in order to approach the problems with the estimation error part of these calculations
- ▶ The introduced randomisation procedure was related to Akaike's FPE and we showed that $FPE = MSEP$ when using an unconditional, complete resampling, procedure
- ▶ Based on the introduced randomisation procedure we also suggested a simple distribution-free formula for calculation of MSEP based on a single first order Taylor expansion
- ▶ The applicability of the approach was illustrated in a number of examples

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Bayesian parameter uncertainty vs frequentist estimation error

- ▶ Let θ^* denote a random parameter vector and let X be defined as above
- ▶ A Bayesian analog of the conditional MSEF is given by the predictive posterior variance of X :

$$\begin{aligned}\text{Var}(X \mid \mathcal{F}_0) &:= \mathbb{E}[(X - \mathbb{E}[X \mid \mathcal{F}_0])^2 \mid \mathcal{F}_0] \\ &= \mathbb{E}[\text{Var}(X \mid \theta^*, \mathcal{F}_0) \mid \mathcal{F}_0] \\ &\quad + \mathbb{E}[(h(\theta^*; \mathcal{F}_0) - \mathbb{E}[h(\theta; \mathcal{F}_0) \mid \mathcal{F}_0])^2 \mid \mathcal{F}_0] \\ &= \mathbb{E}_{\theta^* \mid \mathcal{F}_0}[\text{Var}(X \mid \theta^*, \mathcal{F}_0)] \\ &\quad + \mathbb{E}_{\theta^* \mid \mathcal{F}_0}[(h(\theta^*; \mathcal{F}_0) - \mathbb{E}[h(\theta; \mathcal{F}_0) \mid \mathcal{F}_0])^2]\end{aligned}$$

Bayesian parameter uncertainty vs frequentist estimation error

- ▶ The estimation/uncertainty part in the two MSEP definitions are closely related
- ▶ Depending on assumptions concerning the a priori distribution of θ^* you can, depending on model structure, affect the a posteriori distribution providing heuristic guidance on the specification of $\hat{\theta}^*$
- ▶ Still, θ^* is **truly random** whereas $\hat{\theta}^*$ is a device to capture **uncertainty due to estimation of an unknown parameter vector**

Distribution-free model selection

- ▶ The concept of FPE was originally introduced as a device to be used for model selection for auto-regressive linear models
- ▶ These models are closely related to auto-regressive linear reserving models of the type introduced in e.g. [6]
- ▶ The above discussed techniques could hence be used for distribution-free model selection
- ▶ Other approaches to model selection that are closely connected to the above notion of MSEP is e.g. Mallows' C_p , which in our notation, is based on calculating the following quantity:

$$\mathbb{E}^t[(h^p(\hat{\boldsymbol{\theta}}^p; \mathcal{F}_0) - h^t(\boldsymbol{\theta}^t; \mathcal{F}_0))^2 \mid \mathcal{F}_0]$$

again a situation which can be approached using the introduced techniques